## Introduction to the Mathematical Concepts of CATIA V5

Version 5 Release 19
January 2009
EDU_CAT_EN_MTH_FF_V5R19

## About this course

## Objectives of the course

Upon completion of this course you will be able to:

- Understand the mathematical concepts for curve and surface definition in CATIA V5.


## Targeted audience

GSD and/or FreeStyle users

## Prerequisites

Students attending this course must have knowledge of GSD and FreeStyle Fundamentals

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## The Feature Approach (1/2)

- CATIA V5 supports a FEATURE APPROACH.
- It means that users create and handle objects which are more than mathematical objects because they carry more than just mathematical definitions.
- The mathematical definition of the object is no more than one of the representations of the feature which CATIA may refer to when needed.
. For example, another representation of a surface in CATIA V5 is its triangular mesh used for shaded display or draft analysis.

The Feature Approach (2/2)

FEATURE

## ASSOCIATIVITY INFORMATION



| -parents |
| :--- |
| -creation operator |
| -children |
| $\ldots$ |
|  |

```
-display attributes:
color,
layer,
visibility,
    ...
    -applicative attributes:
    material,
    physical properties,
    tolerances
```



Note: a Datum is a feature with no parents nor creation operator in the asociativity information (it may only have children)

## The Mathematical Level

- The mathematical part of the object definition includes both geometry and topology.
- The geometry defines the shape itself and its location in space,
* The geometry is defined by mathematical objects such as points, vectors, angles, polynomials, ...
- The topology ensures the consistent assembly of the geometrical elements (connections, orientations)
- It is defined by mathematical objects such as vertices, edges, faces


## The Geometry Level for Curves (1/6)

- Curves are described by canonic or parametric forms
- Examples of canonic forms


Line defined by:
-An underlying surface (may be a plane)
-An origin point
-A direction on underlying surface
-A start position
-An end position
Circle defined by:
-underlying surface
-center
-radius
-start angle
-end angle

```
Canonic forms
- are compact (little data)
- are exact
- make it easy to benefit from the
characteristics of the object (example:
select a line to define a direction)
```


## The Geometry Level for Curves (2/6)

- Other types of curves: parametric curves = NURBS

- Non-Uniform

A NURBS curve may be described by several arcs, or spans, or segments. Each segment is described by a parametric form: it has its own set of parametric representations, for example segment number i :
$X=F_{x_{i}}\left(u_{i}\right)$
$Y=F_{Y_{i}}\left(u_{i}\right) \quad$ Note: the segments cannot be separated
$Z=F_{Z i}\left(u_{i}\right)$ by the Disassemble command.

+ possibility to describe more complex shapes with single objects
- segmentation tends to explode if not controlled



## The Geometry Level for Curves (3/6)

## NURBS = Non-Uniform Rational B- $\underline{\text { Spline }}$




With $\mathrm{P}_{\mathrm{xi}}\left(\mathrm{u}_{\mathrm{i}}\right)$ and $\mathrm{Q}_{\mathrm{xi}}\left(\mathrm{u}_{\mathrm{i}}\right)$ being polymomials, ie. mathematical forms such as:
$P_{x i}(u)=A_{0}+A_{1} \cdot u+A_{2} \cdot u^{2}+\ldots+A_{n} \cdot u^{n}$
NURBS created in CATIA V5 are usually polynomial, $Q(u)=1$ this is why they are called NUPBS (P for Polynomial)

+ possibility to describe exact conics, for example a circle can be given by:

$$
X=R \frac{1-u^{2}}{1+u^{2}} \quad Y=R \frac{2 u}{1+u^{2}} \quad \cdots \text { but canonic forms are also exact }
$$

- degrees tend to explode if not controlled example: ruled surface on two curves given by $\frac{P_{1}(u)}{Q_{1}(u)}$ and $\frac{P_{2}(u)}{Q_{2}(u)}$

$S(u, v)=(1-v) \frac{P_{1}(u)}{Q_{1}(u)}+v \frac{P_{2}(u)}{Q_{2}(u)}=\frac{(1-v) P_{1}(u) Q_{2}(u)+v P_{2}(u) Q_{1}(u)}{Q_{1}(u) Q_{2}(u)}$ degrees of polynomials add


## The Geometry Level for Curves (4/6)

## NURBS = Non-Uniform Rational B-ㅇ́spline

- B-Splines


The definition of a B-Spline curves includes the description of the transitions between its segments.

Note: in CATIA V5, NURBS are always internally curvature continuous,
= transitions between segments are always C2.

+ possibility to safely manipulate complex objects, for example to deform complex curves while preserving their overall smoothness (no unexpected gap or sharp corner appearing)
- It may be difficult manipulate the curve while keeping it good looking (example: deform by control points while keeping a nice curvature distribution)



## The Geometry Level for Curves (5/6)



## Note 1: the polygonal representation

- A NURBS can be represented by a polygon = a set of control points
- This representation is often used in style design for intuitive shaping


## Note 2: a special case of NURBS



- A NURBS can be uniform (only one segment)
- It can also be polynomial $\left(Q_{x i}\left(u_{i}\right)=1\right)$

This type of curves is known as Bezier curve It is favored by style designers because it is easier to manipulate (fewer points, well known properties)

## The Geometry Level for Curves (6/6)

General validity criteria for curves:

- A mono-cell curve must be C2 continuous, i.e. mathematically curvature continuous.
- It means that if an action produces a curve that is not C2 continuous, it is cut at each discontinuity and the C2 pieces become cells which are called edges and are assembled in a topology.
- The topology consists in a list of edges with shared vertices (common to several edges) and free vertices (common to one edge only = end points).
- Example: the boundary feature is a single CATIA curve which is not C 2 continuous.
- This CATIA curve is made of several C2 continuous curves called edges that are assembled by a topology (joined).
- The edges may be isolated from each other by an Extract or a Disassemble command (option All Cells).


## The Geometry Level for Surfaces (1/5)

- Surfaces can also described by canonic or parametric forms
- Some surfaces can also be described by their creation process
- Since R14 CATIA V5 also handles subdivision surfaces
- Examples of canonical surfaces:
- Plane
* Cone
- Sphere
- Cylinder
- Torus




## The Geometry Level for Surfaces (2/5)

- Procedural surfaces
- A procedural surface is described by a creation process and the corresponding input

Examples of procedural surfaces:

- Offset surface
defined by a surface + a distance

- Tabulated cylinder defined by a curve, a direction, two lengths
- Linear transformation surface defined by a surface and a geometric transformation



## The Geometry Level for Surfaces (3/5)

- Parametric surfaces $=$ NURBS


The definition for surfaces is similar to the definition for curves with 2 parameters: surfaces may be described by several segments (Non Uniform), each segment is described by a rational form (Rational), but surfaces can be handled globally thanks to B-Spline techniques.
$X=F_{X i}\left(u_{i}, v_{i}\right)=\frac{P_{x i}\left(u_{i}, v_{i}\right)}{Q_{x i}\left(u_{i}, v_{i}\right)}$
$Y=F_{Y_{i}}\left(u_{i}, v_{i}\right)$
$Z=F_{z i}\left(u_{i}, V_{i}\right)$

## Notes:

- NURBS created in CATIA V5 are usually (almost always) polynomials (NUPS)
- they are always curvature continuous (C2),
- NURBS surfaces can be represented and handled by control points,
- uniform polynomial NURBS are known as Bezier patches


## The Geometry Level for Surfaces (4/5)



- Subdivision surfaces

Subdivision is an algorithmic technique to generate smooth surfaces as a sequence of successively refined polyhedral meshes.


## Advantages:

A complex object can be represented with only one multi-faced surface
The surface is refined only where required (details) => Easy manipulation + Data size reduced


## Student Notes:

## The Geometry Level for Surfaces (5/5)

General validity criteria for surfaces:

- A mono-cell surface must be C2 continuous.
- It means that if an action produces a result that is not C2 continuous, it is cut at each discontinuity and the C2 pieces become cells which are called faces and are assembled in a topology.
- Example: the sweep feature is a single surface which is not C2 continuous (not even C1 in this case). It is made of several C2 continuous faces that are assembled by a topology (joined). The geometric surfaces may be isolated from each other by a Disassemble command (option All Cells).



